

# *A Penetrator for the Jupiter Ganymede Orbiter Mission*

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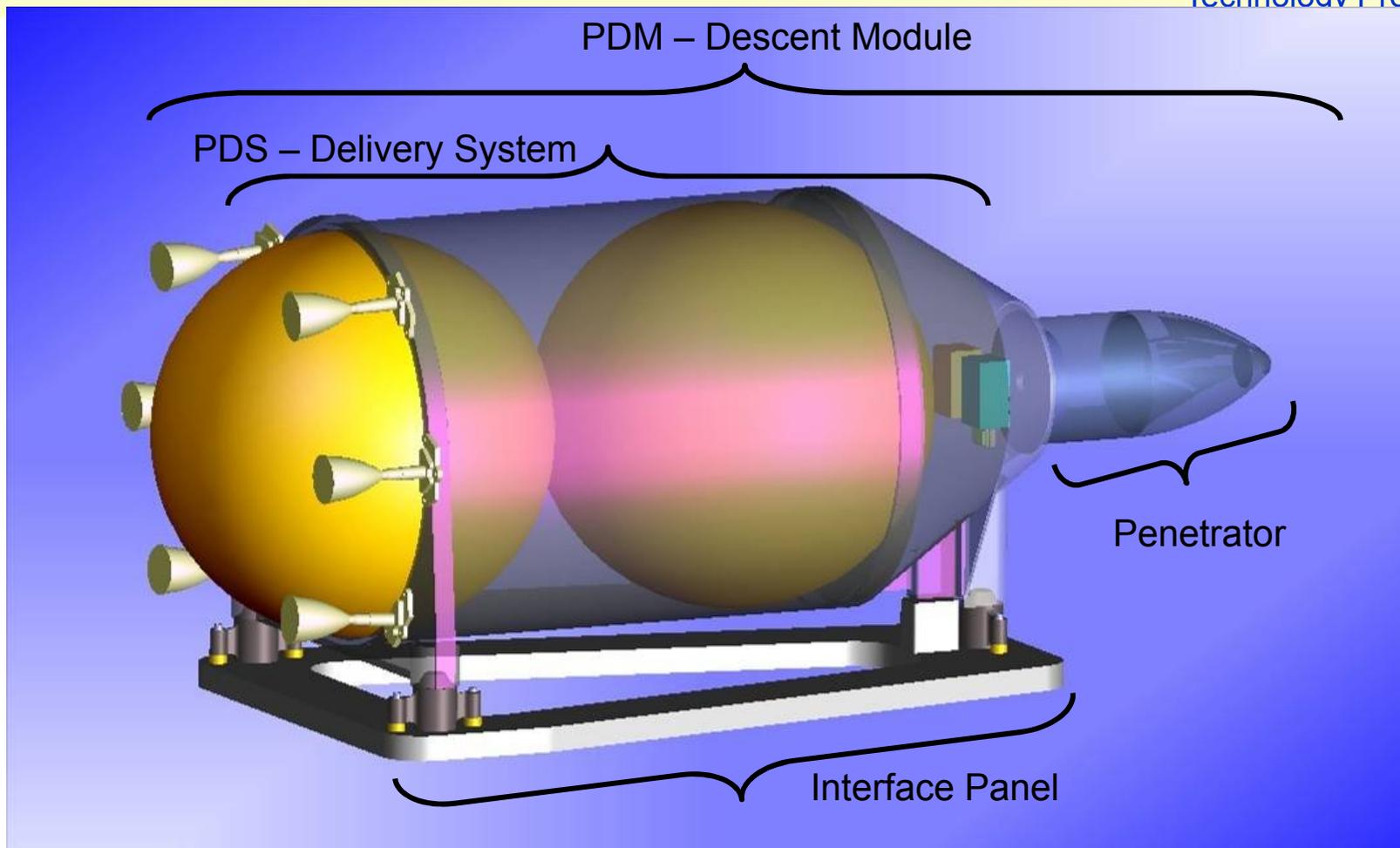
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# Configuration Overview

Advanced Studies and  
Technology Preparation



## Study inputs & Constraints

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- Compatible with JGO mission configuration**
  
- Minimum science payload with a GEOPHYSICS focus (for Ganymede)**
  
- Mass limit of 100kg**
  
- Technologies at TRL5 by 2012**
  
- Feasible and low risk**

# “Release Location” Scenario Comparison

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## Single Penetrator

- Hyperbolic Approach
  - Callisto Pseudo Orbit
  - Ganymede Final Orbit

Target	Mission phase	Impulsive De-orbit Delta-V (m/s)
<b>Hyperbolic cases</b>		
Ganymede	Pre-capture	<b>7698</b>
Callisto	Callisto Pseudo orbit tour	<b>3192</b>
Ganymede	Final approach	<b>2864</b>
<b>Ganymede “final orbits”</b>		
Ganymede	Elliptical orbit	<b>2474</b>
<b>Ganymede</b>	<b>Circular orbit</b>	<b>1955</b>

## “Applied Science Approach ” Scenario Comparison

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### ❑ Trade-off between

- **Single Penetrator** (baseline cases for each release location)
- Multiple Penetrators
- Multiple Moons
- Semi-Hard Landers

## Baseline Scenario Selection

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**❑ A Single Penetrator, released from Ganymede 200km circular orbit is proposed**

**❑ No other scenario is considered feasible assuming a 7.5kg Penetrator landed element and a maximum 100kg of system (Penetrator + PDS) mass.**

**❑ Smaller Penetrators (~ few kg) are not considered feasible:**

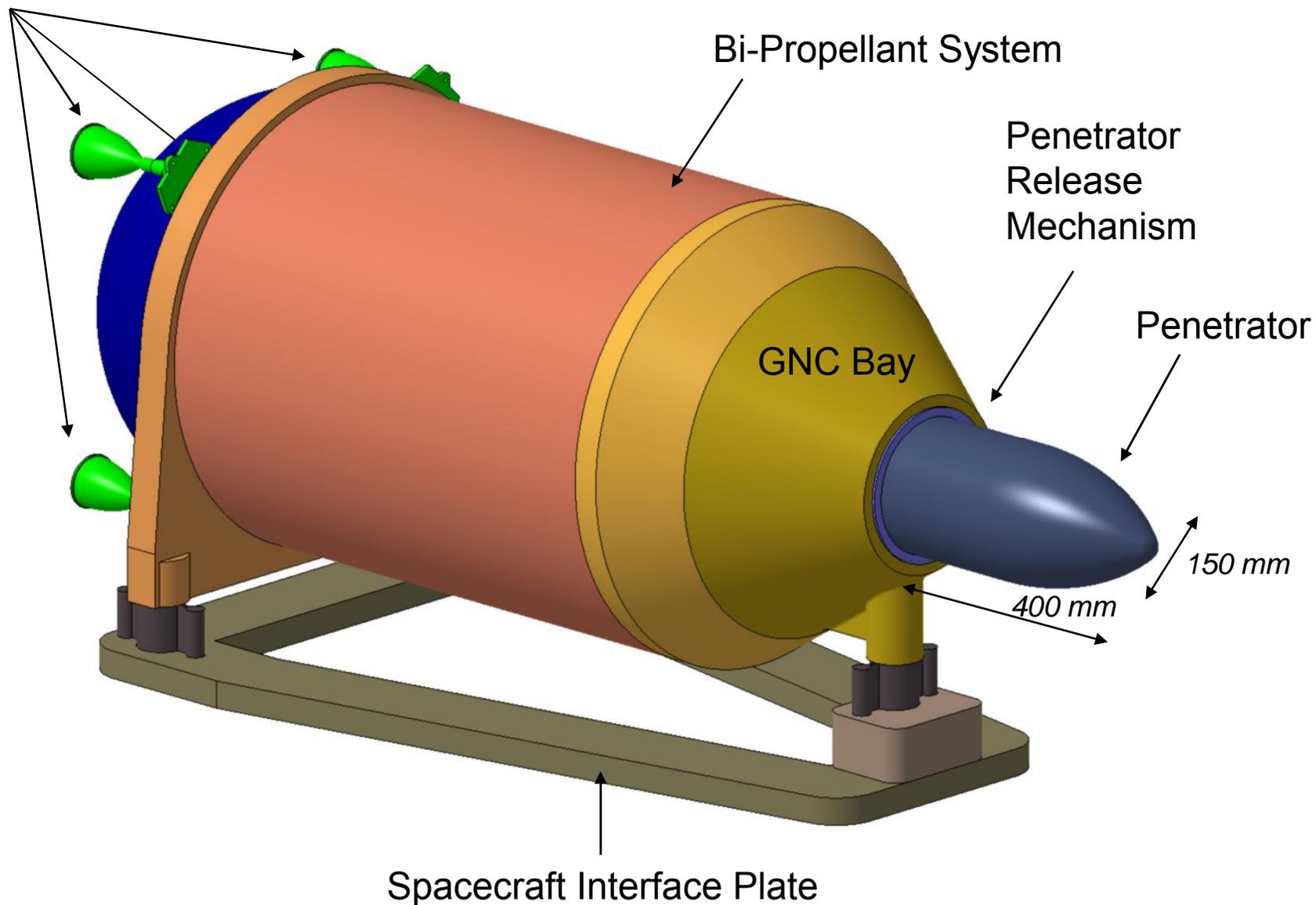
- tiny payload,
- large heat loss

→ multiple penetrator / multiple targets not possible.

# PDM configuration

6 x 31N Thrusters

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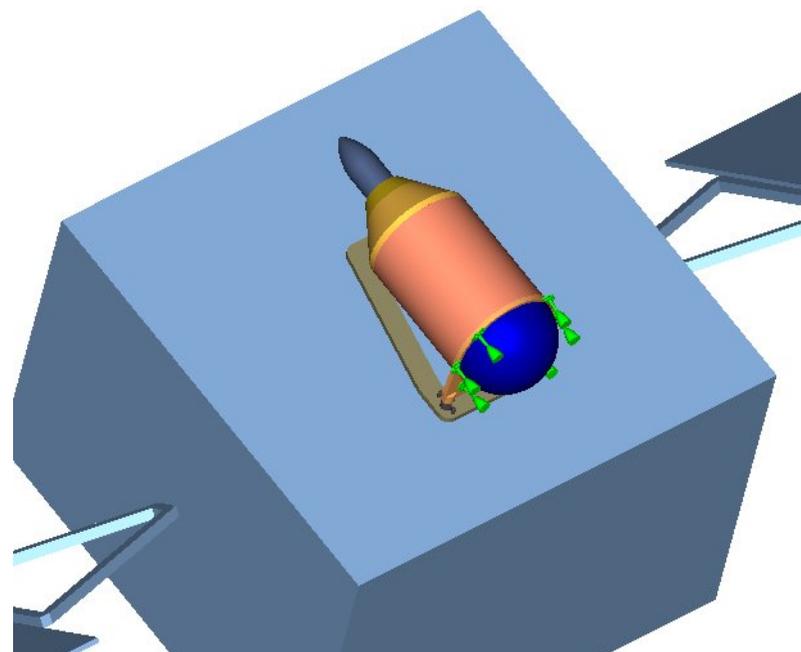
# Accommodation on JGO

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Dimension	Value
Mounted Length	1200 mm
Mounted Width	500 mm
Height	700 mm

Limited power (14W) and data will be required from JGO during cruise

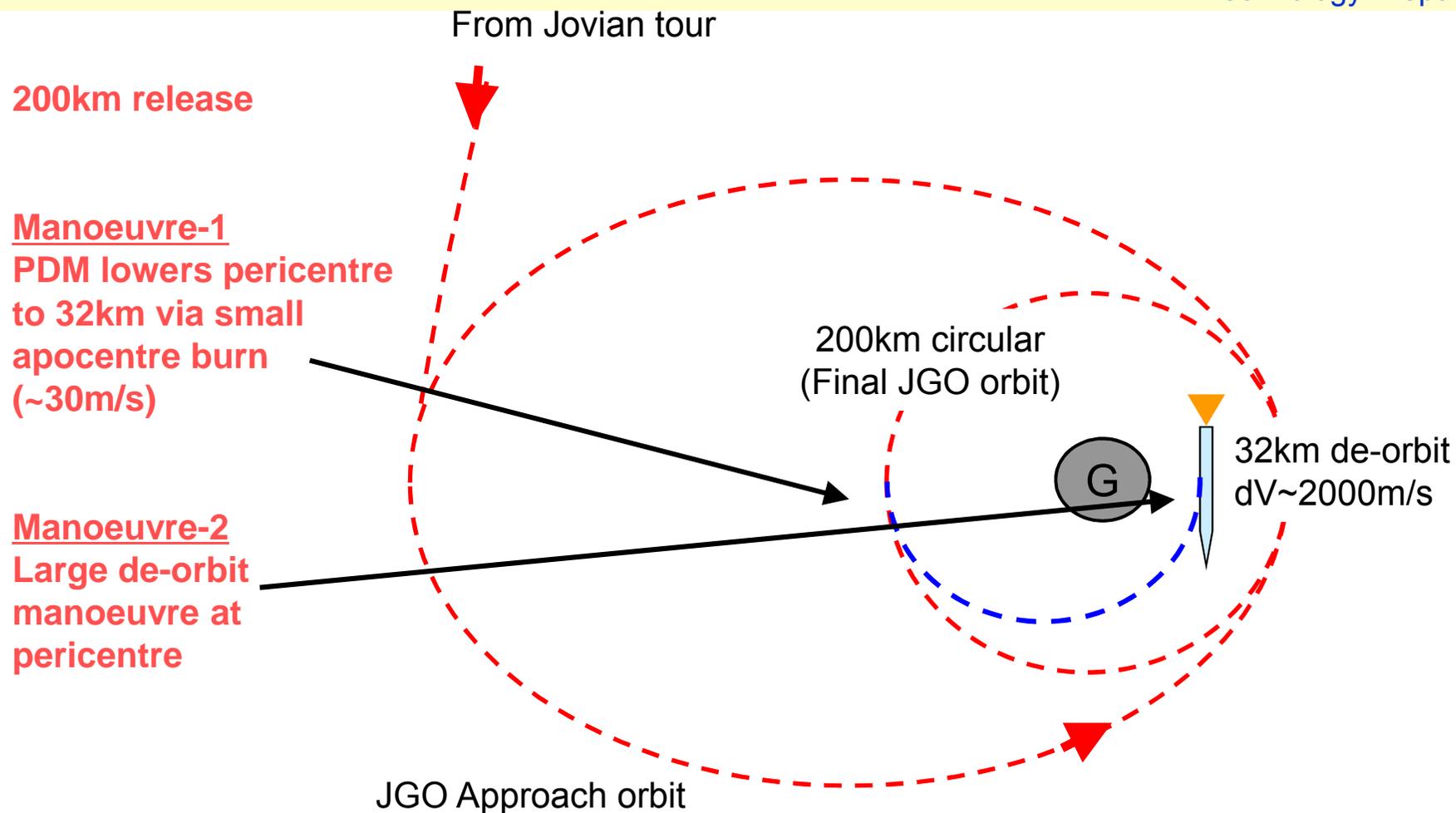
Shared Planetary Protection categorisation of II+ with JGO



Interface Panel simplifies interface to JGO

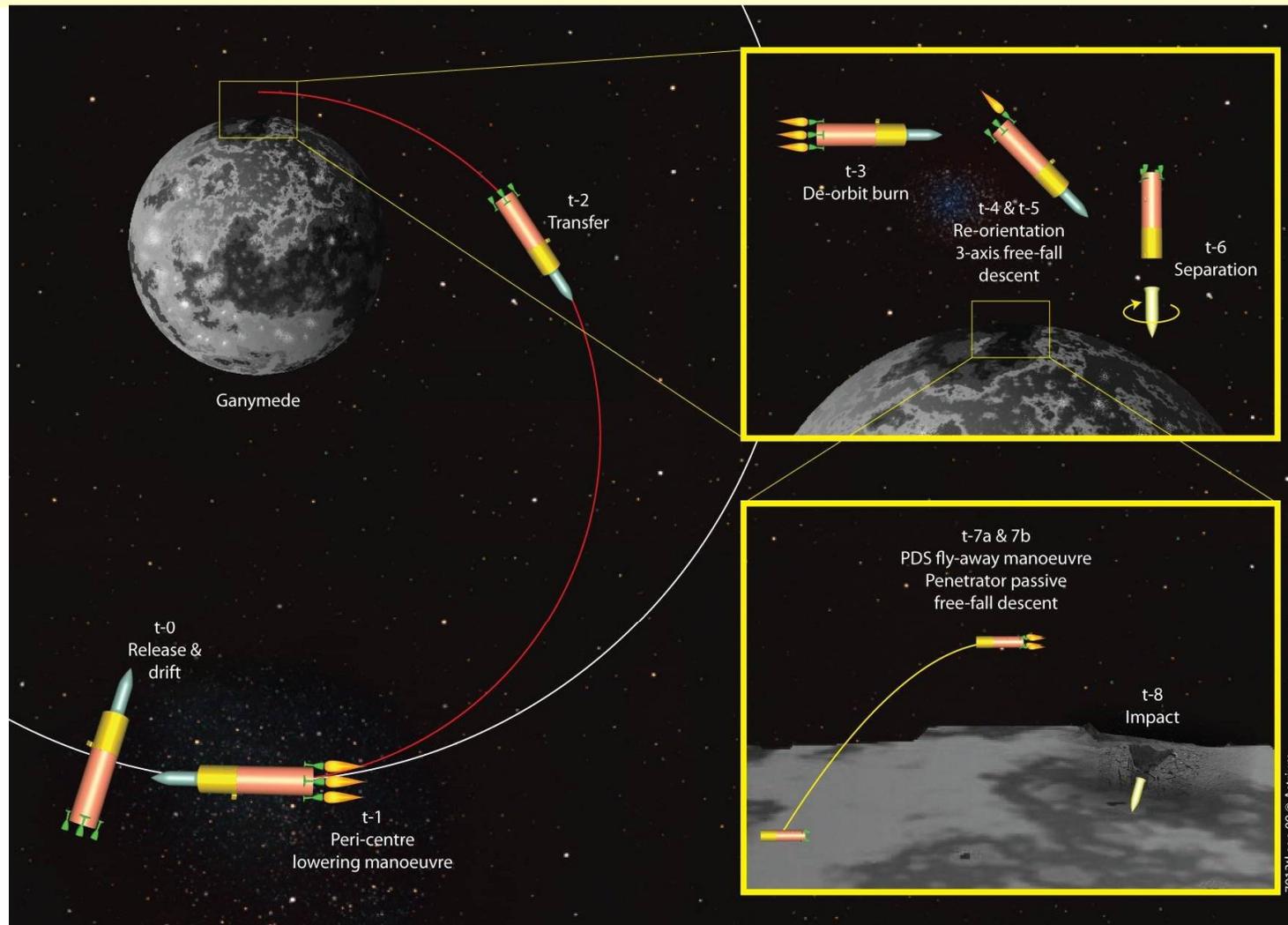
# Simplified Release Sequence (Impulsive case)

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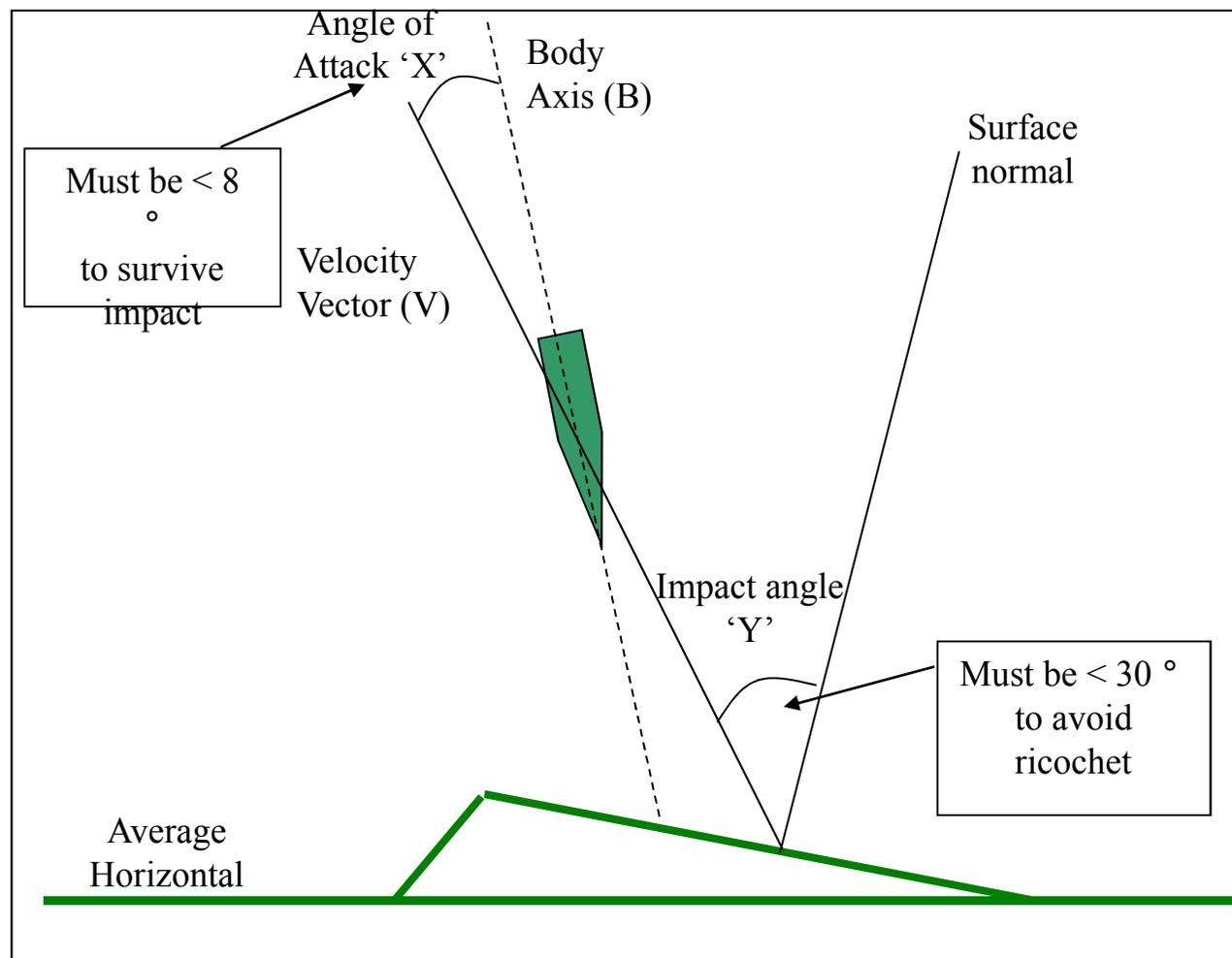
# JGO Penetrator – Baseline Descent Scenario

Advanced Studies and Technology Preparation



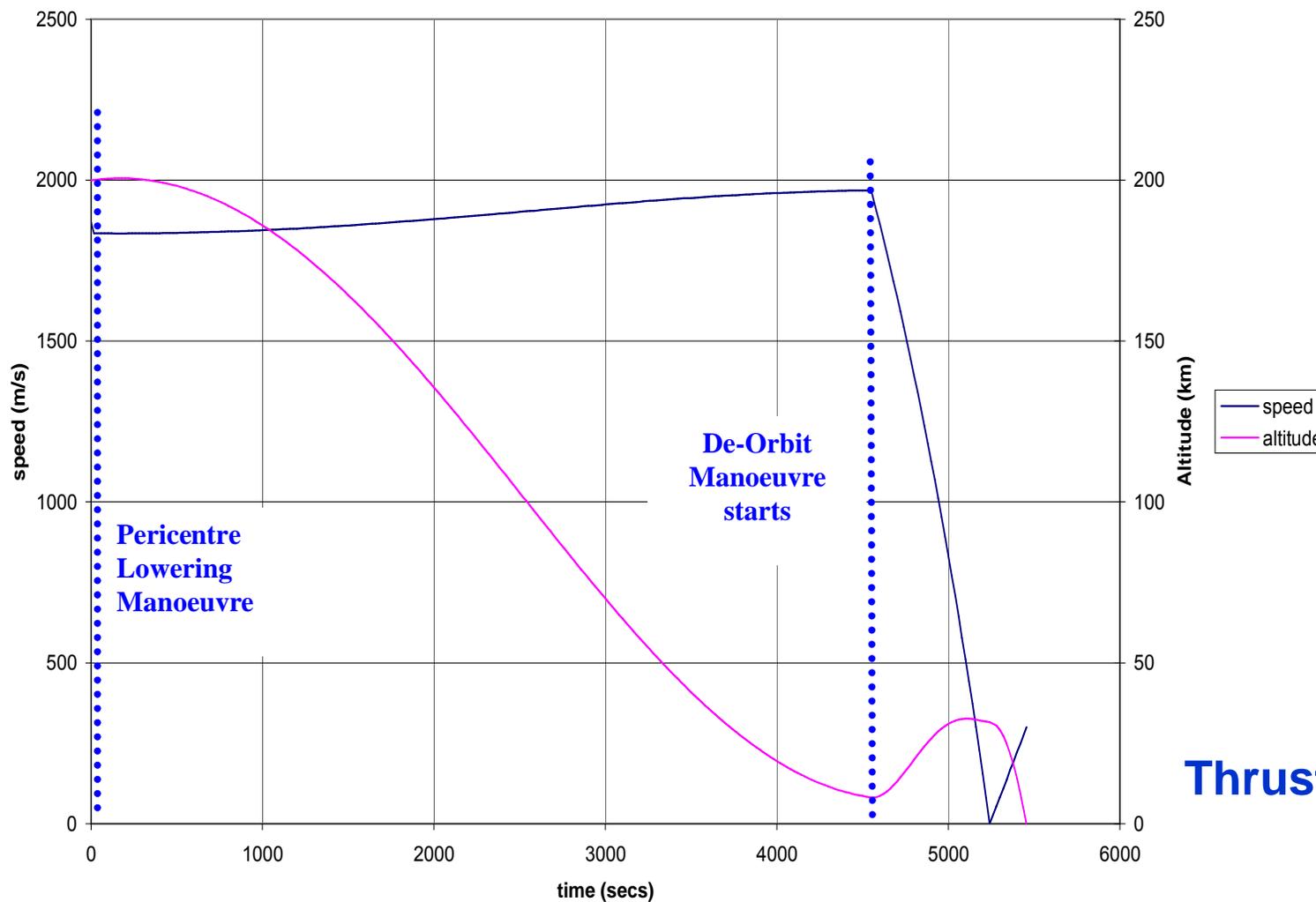
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# PDS Delivery Constraints



# PDM Descent Sequence ('Real' Non-Impulsive case)

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**Thrust = 180N**

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## Propulsion and GNC solution

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### □ Propulsion

- Blow-down Bi-Prop System
- 6-off 22N Thrusters (running over-pressure to achieve 31N each)
- Off-axis canted to provide 3-axis control

### □ GNC

- MEMS Inertial System (QRS11 x 3 + 1 for redundancy = 4 total)
- Miniature Star Tracker
- 3-axis Control throughout following an initial attitude acquisition

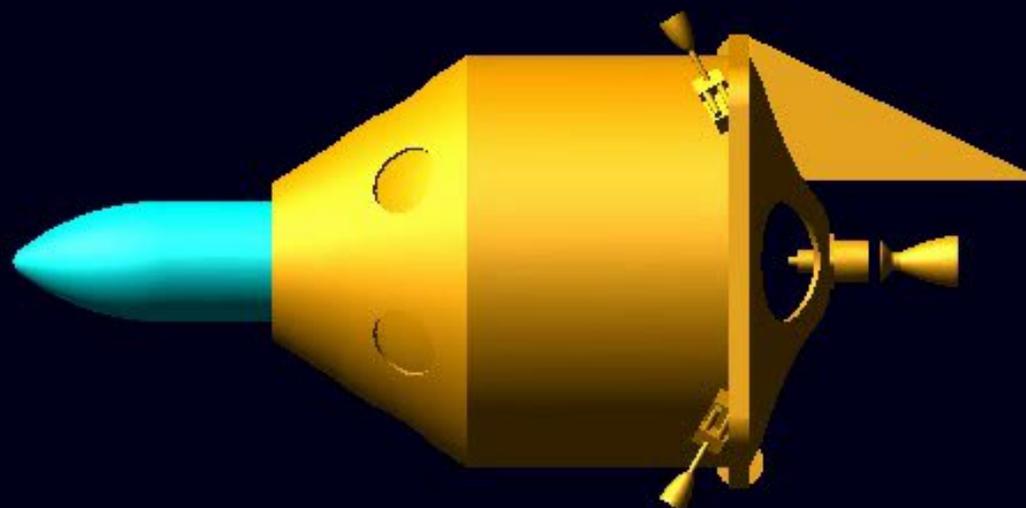
*All technologies compatible with TRL 5 by 2012*

## Conclusions on GNC analysis

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- **Mission achievable from AOCS perspective**
- **Sensor architecture:**
  - **Micro Star tracker plus rate sensor is a viable solution**
  - **Accommodation issues (mass, power, space) limit redundancy options**
- **Control architecture:**
  - **Same basic architecture can be used from JGO separation to spin-up phase**
  - **Following spin-up, open loop control is possible, but relies on high spin-rate**
- **Performance:**
  - **Goal performances for descent angle ( $<7^\circ$ ) & AoA ( $< 8^\circ$ ) and landing ellipse ( $< 15\text{km}$ ) can be met**

Last\_Run Time= 0.0000 Frame=00001



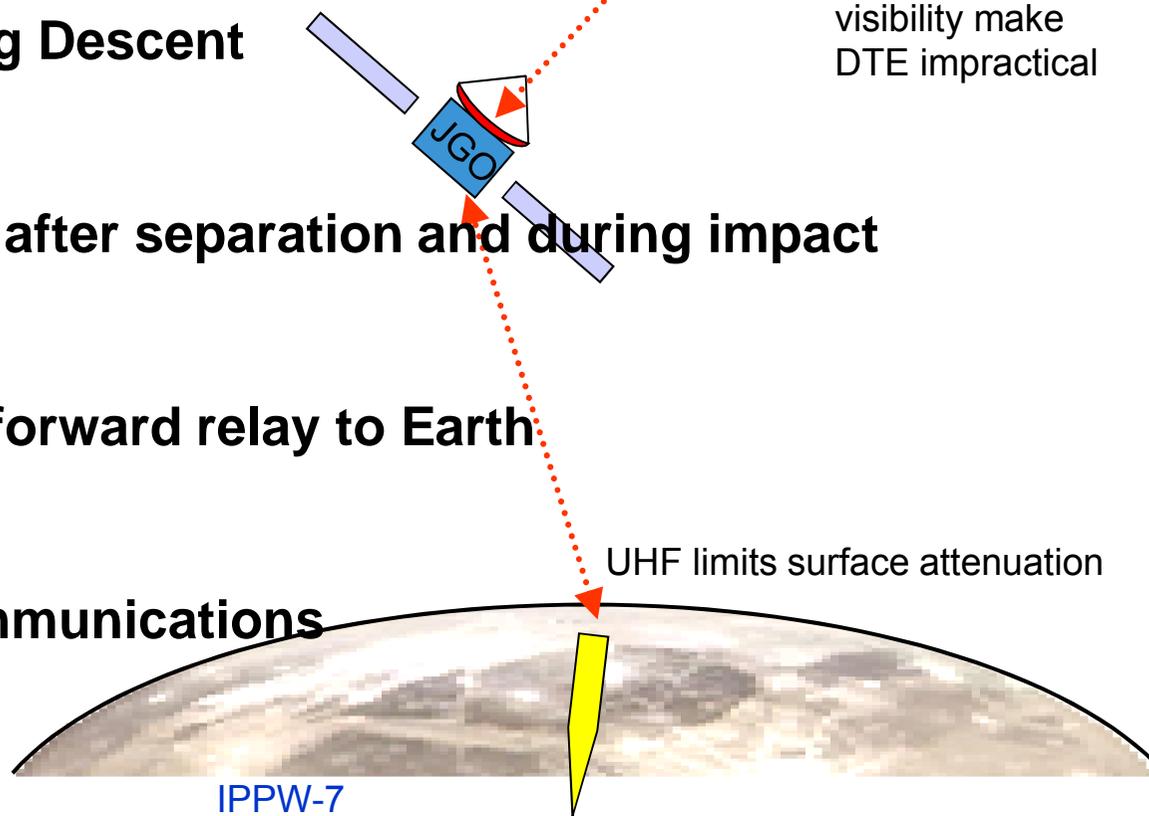
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# Communications Architecture

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- ❑ PDM / Penetrator uses Prox-1 UHF band (~400MHz)
- ❑ PDM to JGO link during Descent
- ❑ Penetrator to JGO link after separation and during impact
- ❑ JGO provides store & forward relay to Earth
- ❑ No Direct to Earth Communications

Frequency,  
power, &  
visibility make  
DTE impractical



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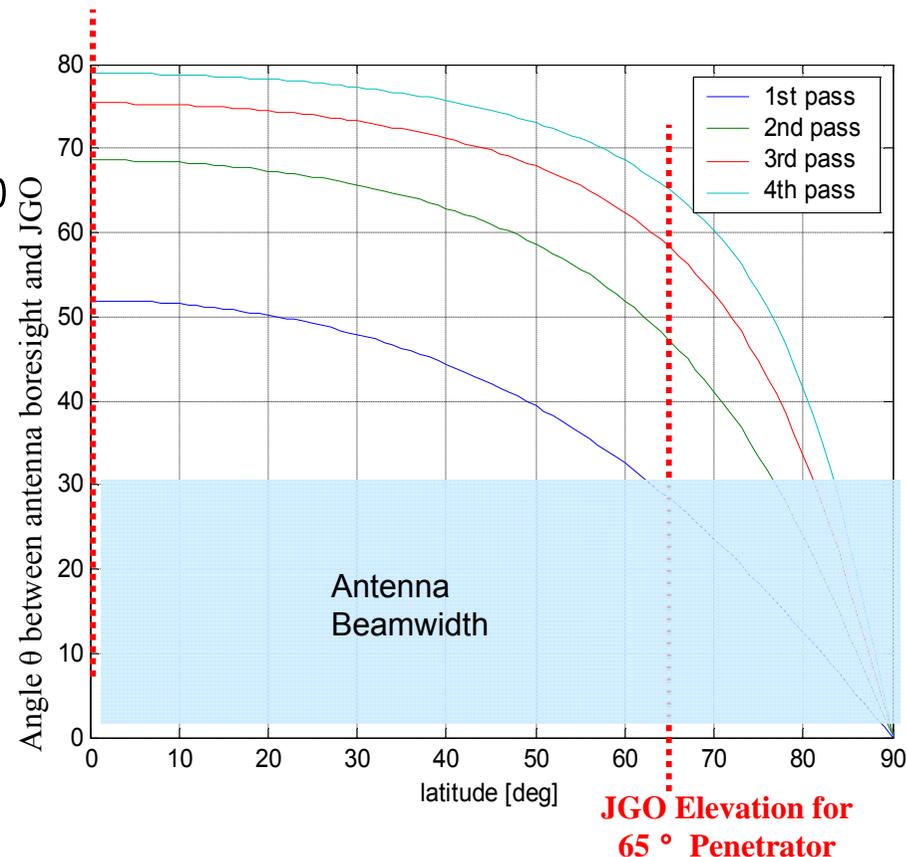
# Communications on the 2<sup>nd</sup> Pass

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- 2nd Orbit ~3 hours after impact
- Next 'overhead' pass ~3.5 Earth days later
- If thermal system fails, then core temperature will drop below operating range in a few hours
- If battery outlives the baseline mission, then an extended mission is unlikely to last 3.5 days (few hours max)

2nd Orbit visibility taken as a requirement

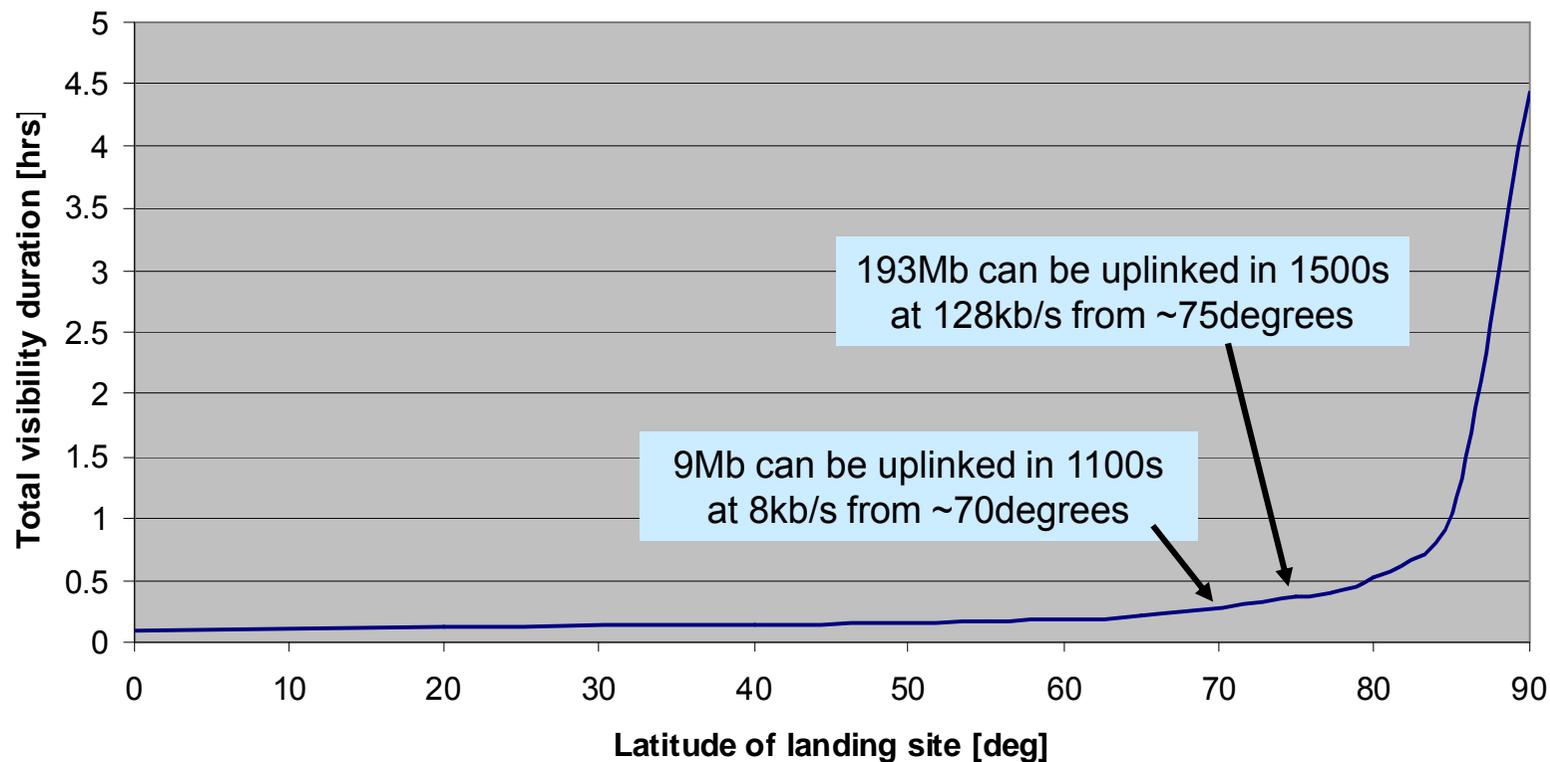
**JGO Elevation for Equatorial Penetrator**



# Data Volumes

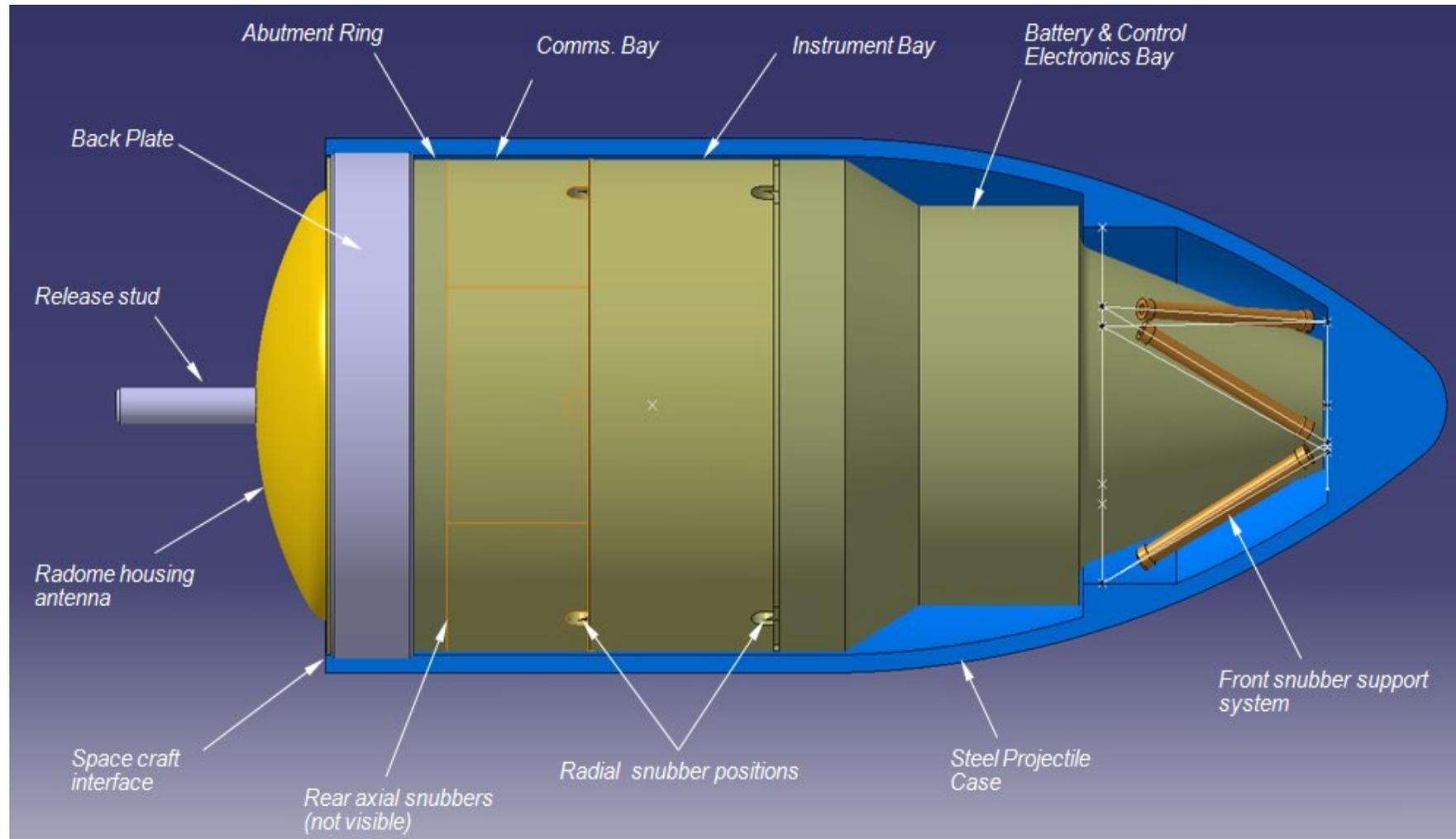
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Total visibility duration over 2 rotation periods (i.e. 343.2 hrs)



# JGO Penetrator

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# Penetrator Mass breakdown

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Penetrator Sub-Systems	Margin	System Mass [Kg]
Instruments only Mass	50%	0.8 kg
Sub-System + Instruments Mass Excluding Shell		7.0 kg
System Margin	20%	
Sub-System + Instruments Mass WITH MARGIN		8.4 kg
Penetrator Shell Mass (no margin)		6.1 kg
System Margin	20%	
Penetrator Shell WITH MARGIN		7.3 kg
<b>PENETRATOR TOTAL MASS</b>		<b>15.7 kg</b>

## Penetrator + Delivery System Mass

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Subsystem	Margin [%]	System Mass [Kg]
PDS Dry Mass (no Penetrator)		22.8 kg
System Margin	20%	
PDS Dry Mass Including margin		27.3 kg
Propellant mass		43.6 kg
PDS TOTAL MASS (no Penetrator)		70.9 kg
Penetrator mass (incl. Margin)		15.7 kg
PDM Dry Mass (incl Pen.)		43.0 kg
<b>DESCENT MODULE TOTAL MASS</b>		<b>86.6 kg</b>

## System mass sensitivity

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Wet PDS mass to deliver itself (w/o Penetrator) to surface = 40kg

Multiplication factor for propulsion elements for a given Penetrator dry mass is about 3 (fuel, thrusters, tanks, supports).

5kg Penetrator + 10kg propulsion = 15kg .... System mass => 40+15 = 55kg

10kg Penetrator + 20kg propulsion = 30kg .... System mass => 40+30 = 70kg

15kg Penetrator + 30kg propulsion = 45kg .... System mass => 40+45 = 85kg

With some additional resource-sharing, potentially the PDS mass could be reduced by max a few kgs, thus saving max 5kg on the system mass.

**Bottom line: For JGO-Penetrator, 65kg (incl. margin) would be the absolute bottom limit to deliver a meaningful (10kg) Penetrator to the surface.**

## Major risks

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- ❑ **Developmental – TRL 5 by 2012**
  - Penetrator Battery
  - Instrumentation shock tolerance
- ❑ **Limited FDIR**
  - e.g. Single Thruster failure – limited chance of recovery
- ❑ **Thermal Short**
  - Lifetime of hours only
- ❑ **Surface unknowns**
  - Over-steep terrain (risk of ricochet)
  - Out of range material hardness (impact survival, cratering, penetration depth)
  - Out of range dielectric properties (RF attenuation)
  - **Ultimately, unknowns about the surface material properties remain and add significant risk to the mission**

## Conclusions

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- ❑ Penetrators for the Outer Moons are possible, but **THEY WON'T BE TINY...**
- ❑ In order to maintain a small package, not all risks can be mitigated, so a mission will be **INHERENTLY MORE RISKY** than soft landers.
- ❑ Lack of atmospheres, hard surfaces, low temperatures and large delta-Vs make the use of Penetrators on the Jovian moons **VERY CHALLENGING.**
- ❑ **NICHE OPPORTUNITIES EXIST** when small mass margin on an orbiter mission is available and offers **LIMITED BUT UNIQUE SCIENCE RETURN.**